AMENDMENTS TO THE CLAIMS

1. (currently amended) A method to determine the presence of an-electrical machine a brushless DC (BLDC) motor connected to an electronic control circuit, the electronic control circuit operative to control the BLDC motor having one or more magnetic components, the method comprising:

generating a pulse signal to a selected driven phase winding through at

least four inverter transistors configured within the electronic control circuit; and

detecting said pulse signal for the purpose of one of a signal presence and

absence thereof at a non-driven phase winding as a result of said pulse signal,

wherein presence of said signal at said non-driven phase winding is

indicative of the motor connected to the electronic control circuit.

- 2. (original) The method of claim 1, wherein absence of said signal at said non-driven phase winding is indicative of the electric machine lacking connection with the electronic control circuit.
- 3. (original) The method of claim 1, wherein said generating said pulse signal includes an arbitrary sequence of pulses.
- 4. (original) The method of claim 1, wherein said generating said pulse signal includes one of a random sequence and a pseudo random sequence of pulses.
 - 5. (cancelled)
- 6. (original) The method of claim 1, wherein said signal non-driven phase winding includes non-driven phase windings adjacent said driven phase winding.
 - 7. (cancelled)

- 8. (currently amended) The method of claim 3, wherein the electronic control circuit is receptive to said arbitrary sequence of signals and feedback signals from the electrical machine motor.
- (original) The method of claim 8, wherein the electronic control circuit is configured to determine signal presence or absence thereof at said non-driven phase winding.
- 10. (currently amended) The method of claim 71, further including:
 activating only two of the at least four inverter transistors to generate pulse signals to determine the presence of the motor.
- 11. (currently amended) The method of claim 71, further including:
 activating three of the at least four inverter transistors to generate pulses to determine the presence of the motor.
- 12. (currently amended) The method of claim 71, further including:

 chabling all of the at least four inverter transistors for one of a single pulse and a plurality of pulses for the purpose of detection of one of the motor or a load.
- 13. (original) The method of claim 1, wherein a detection duty cycle is less than 50% such that a current in said selected driven phase winding always decays to zero during said detecting said pulse.
- 14. (original) The method of claim 1, wherein a detection duty cycle is greater than 50% such that a current in said selected driven phase winding never decays to zero and accumulates over successive sequences of said detecting said pulse.
 - 15. (currently amended) A system to determine the presence of an electrical

machine a brushless DC (BLDC) motor connected to an electronic control circuit, the electronic control circuit operative to control the BLDC motor having one or more magnetic components, comprising:

a stator having a plurality of phase windings; and

an-the electronic control circuit configured to generate a pulse signal to a selected driven phase winding through at least four inverter transistors configured within the electronic control circuit, said pulse signal detected for the purpose of one of a signal presence and absence thereof at a non-driven phase winding as a result of said pulse signal, wherein presence of said signal at said non-driven phase winding is indicative of the motor connected to the electronic control circuit.

- 16. (original) The system of claim 15, wherein absence of said signal at said non-driven phase winding is indicative of the electric machine lacking connection with the electronic control circuit.
- 17. (original) The system of claim 15, wherein generating said pulse signal includes an arbitrary sequence of pulses.
- 18. (original) The system of claim 15, wherein generating said pulse signal includes one of a random sequence and a pseudo random sequence of pulses.
 - 19. (cancelled)
- 20. (original) The system of claim 15, wherein said signal non-driven phase winding includes non-driven phase windings adjacent said driven phase winding.
 - 21. (cancelled)
 - 22. (currently amended) The system of claim-1817, wherein the electronic

control circuit is receptive to said arbitrary sequence of signals and feedback signals from the electrical machinemotor.

- 23. (original) The system of claim 22, wherein the electronic control circuit is configured to determine signal presence or absence thereof at said non-driven phase winding.
- 24. (currently amended) The system of claim-2215, wherein only two of the at least four inverter transistors are activated to generate pulse signals to determine the presence of the motor.
- 25. (currently amended) The system of claim-2215, wherein three of the at least four inverter transistors are activated to generate pulses to determine the presence of the motor.
- 26. (currently amended) The system of claim 2015, wherein all of the at least four inverter transistors are enabled for one of a single pulse and a plurality of pulses for the purpose of detection of one of the motor or a load.
- 27. (original) The system of claim 15, wherein a detection duty cycle is less than 50% such that a current in said selected driven phase winding always decays to zero during said detecting said pulse.
- 28. (original) The system of claim 15, wherein a detection duty cycle is greater than 50% such that a current in said selected driven phase winding never decays to zero and accumulates over successive sequences of said detecting said pulse.
- 29. (currently amended) A storage medium encoded with a machine-readable computer program code, said code including instructions for causing a computer to

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generating a pulse signal to a selected driven phase winding through at least four inverter transistors configured within the electronic control circuit; and detecting said pulse signal for the purpose of one of a signal presence and absence thereof at a non-driven phase winding as a result of said pulse signal, wherein presence of said signal at said non-driven phase winding is indicative of the motor connected to the electronic control circuit.